

TMC10 Dozer Control System User Guide

Dozer 3D Guidance System

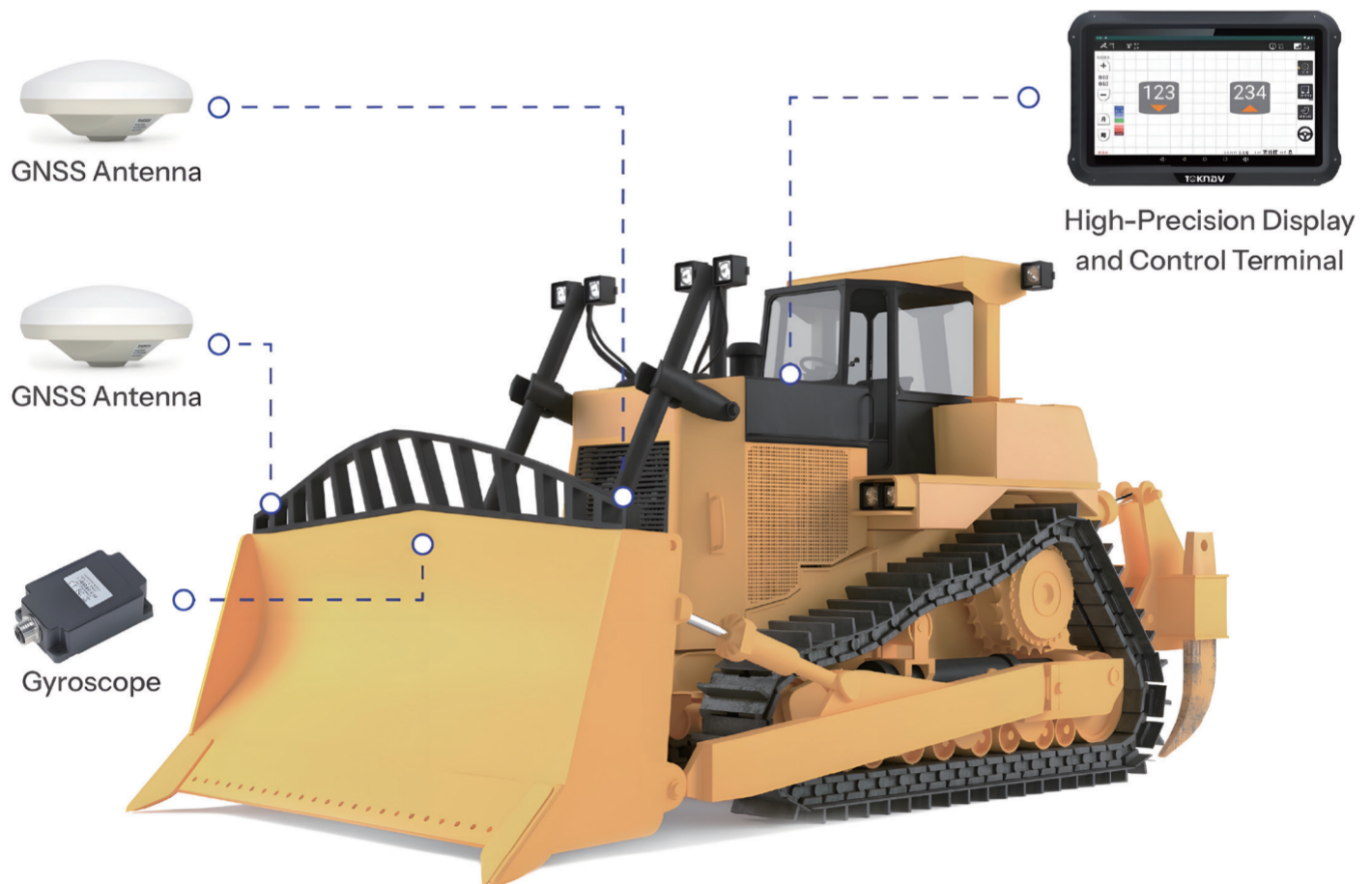


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1. System Operating Principle

The dozer system utilizes sensors mounted at the blade's midpoint to measure its attitude, complemented by dual satellite antennas (GPS300) installed on both sides to receive positioning signals for precise blade location and elevation calculation. Data from sensors and antennas transmit via main cables to the controller, where GNSS modules and ECU process the information. Real-time blade positioning and orientation data are then relayed to the in-vehicle tablet. Operators can set reference planes or import design files via the tablet interface, enabling manual blade height adjustments through visual feedback.



2. Software Interface

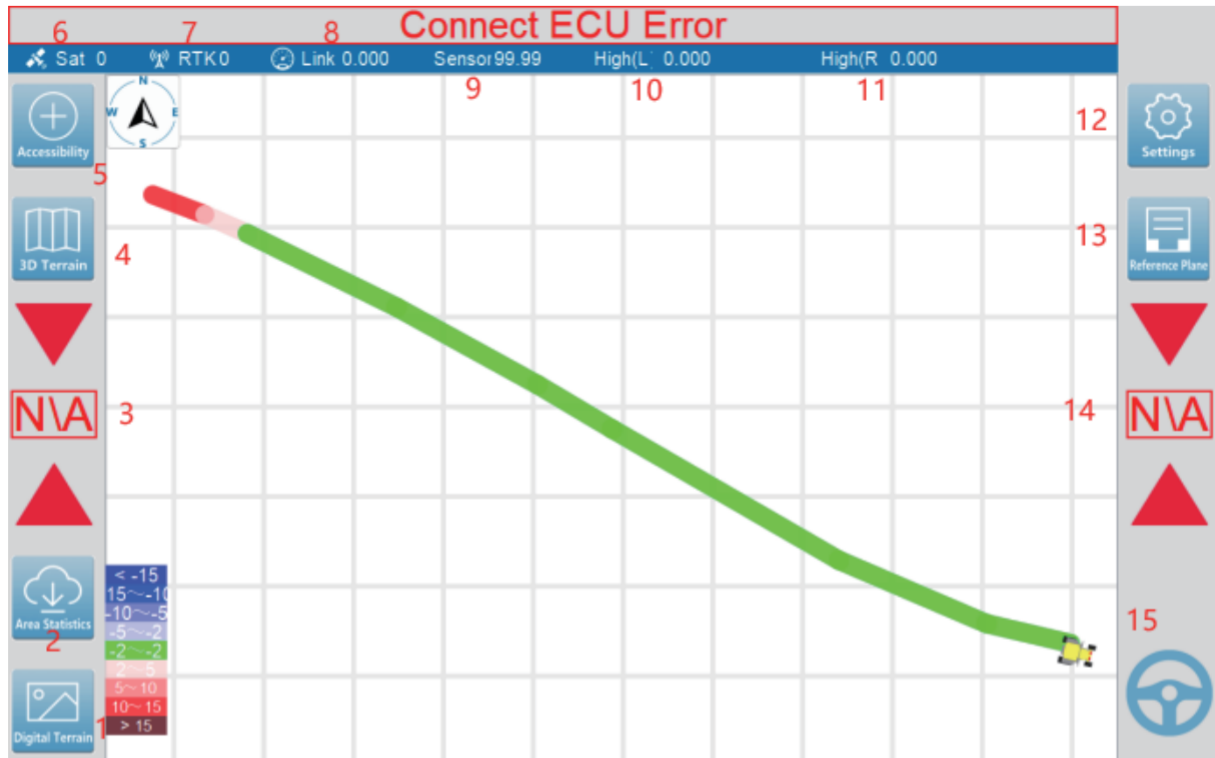


Figure 1 Software Interface

1. Digital Terrain
2. Area Statistics
3. Reference Plane Height Difference
4. 3D Terrain
5. Accessibility (Not Yet Available)
6. Number of Satellites
7. RTK Status
8. Differential Delay
9. Sensor Parameters
10. Blade Left Side Height
11. Blade Right Side Height
12. Settings
13. Reference Plane Settings
14. Reference Plane Height Difference
15. Manual/Automatic Mode Switch

3. Basic Settings

3.1. Base Setup

- (1)Deploy a GNSS receiver as a base station configured with built-in radio modem data link.
- (2)Set the radio protocol to Transparent Transmission Protocol (e.g., PCC-GMSK) and frequency to 450.0125 MHz – matching the dozer system's default settings.
- (3)Ensure the dozer (rover) uses identical protocol and frequency to maintain seamless communication with the base station.

3.2 Coordinate System Settings

Click Setting – System Tool – Coordinate

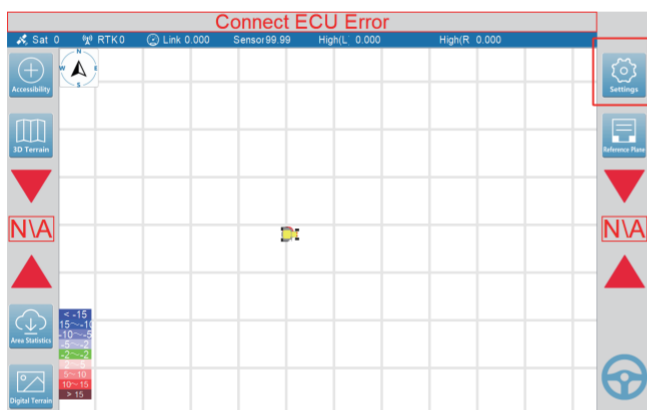


Figure 2 Settings

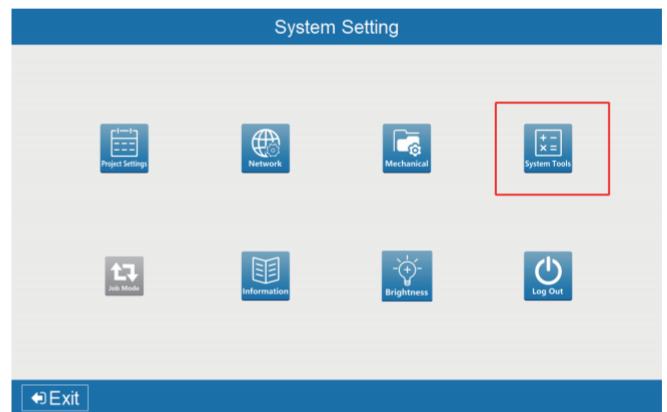


Figure 3 System Setting

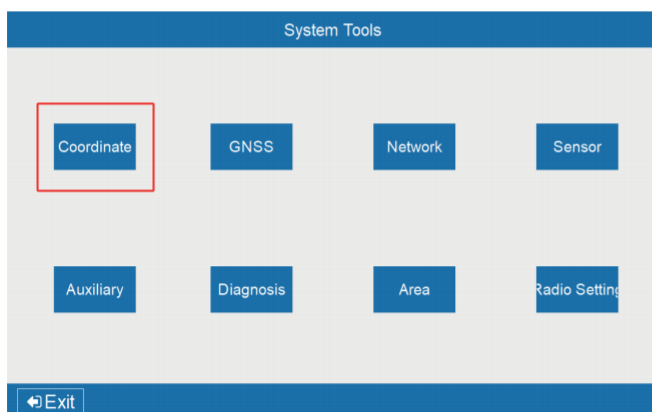


Figure 4 Coordinate

3. Basic Settings

WGS84

Ellipsoid 7 Para 4 Para High Para

ajor semi-axis A: 0

Flattening F: 0

 Notice:
1.After entering each parameter, click "Set";
2.view the parameters need to click "get configuration" to download the parameters be

Exit Get Set

Figure 5 Coordinate System Parameters

Clicking on WGS84 multiple times allows you to switch between the Xi'an 1980, Beijing 1954, WGS84, and custom coordinate systems.

WGS84

Ellipsoid 7 Para 4 Para High Para

X(m) 0 X(") 0

Y(m) 0 Y(") 0

Z(m) 0 Z(") 0

K(ppm) 0 Projected Longitude(°) 0

• 6 Degree Bar • 6 Degree Bar

Exit Get Set

Figure 6: 7-Parameter and Central Meridian & Zone Settings

3. Basic Settings

WGS84

Ellipsoid7 Para4 ParaHigh Para

D0

A(°)0

D0

K0

Open

Exit

Get

Set

Figure 7 4-Parameter Settings

WGS84

Ellipsoid7 Para4 ParaHigh Para

A0

A30

A10

A40

A20

A50

X00

Y00

Open

(Formula: $A_0+A_1*x+A_2*y+A_3*x*x+A_4*y*y+A_5*x*y+h=0$)

Exit

Get

Set

Figure 8 Height Settings

3. Basic Settings

3.3 Blade and Antenna Model Parameters Settings

Click Mechanical – User

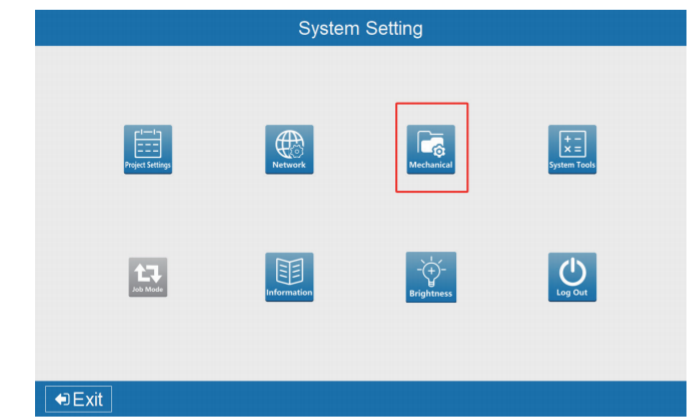


Figure 9 Mechanical



Figure 10 User

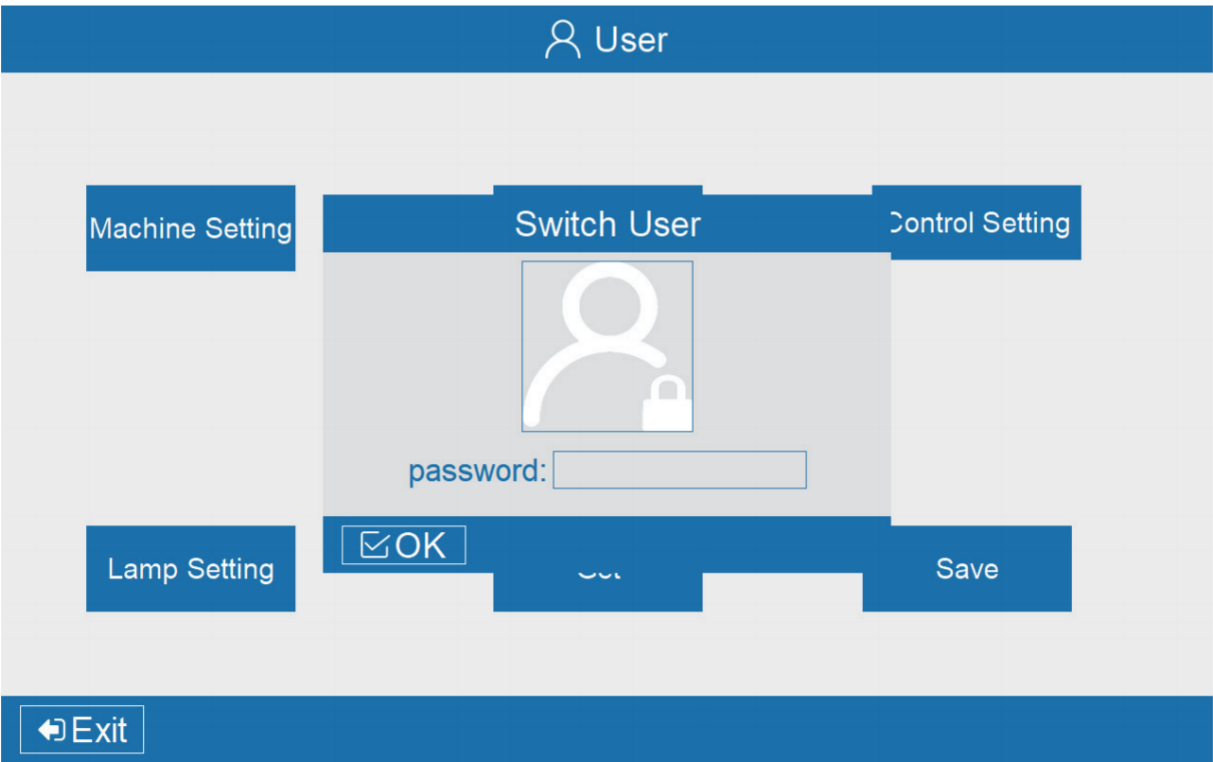


Figure 11 Enter the password to switch to administrator mode (password: 123456).

3. Basic Settings

Click Machine Setting



Figure 12 Admin

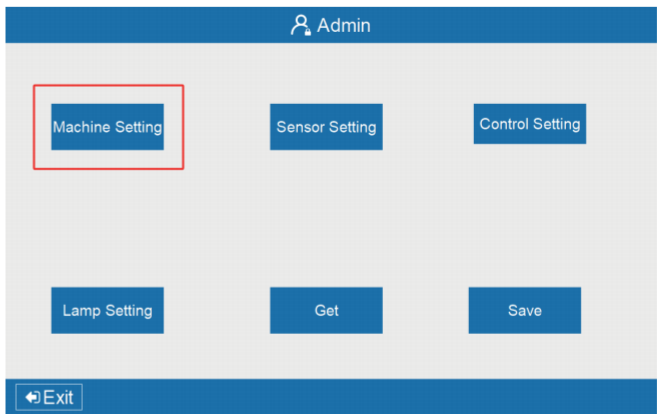


Figure 13 Machine Setting

Current Left(Switch)

3NSS antenna to blade tip vertical distance:

0

m

NSS antenna to left edge of blade(inside :+):

0

m

5NSS antenna to blade front(backward :+):

0

m

Blade width:

0

m

Exit

Get

Set

Figure 14 Left Blade Parameters Setting

3. Basic Settings

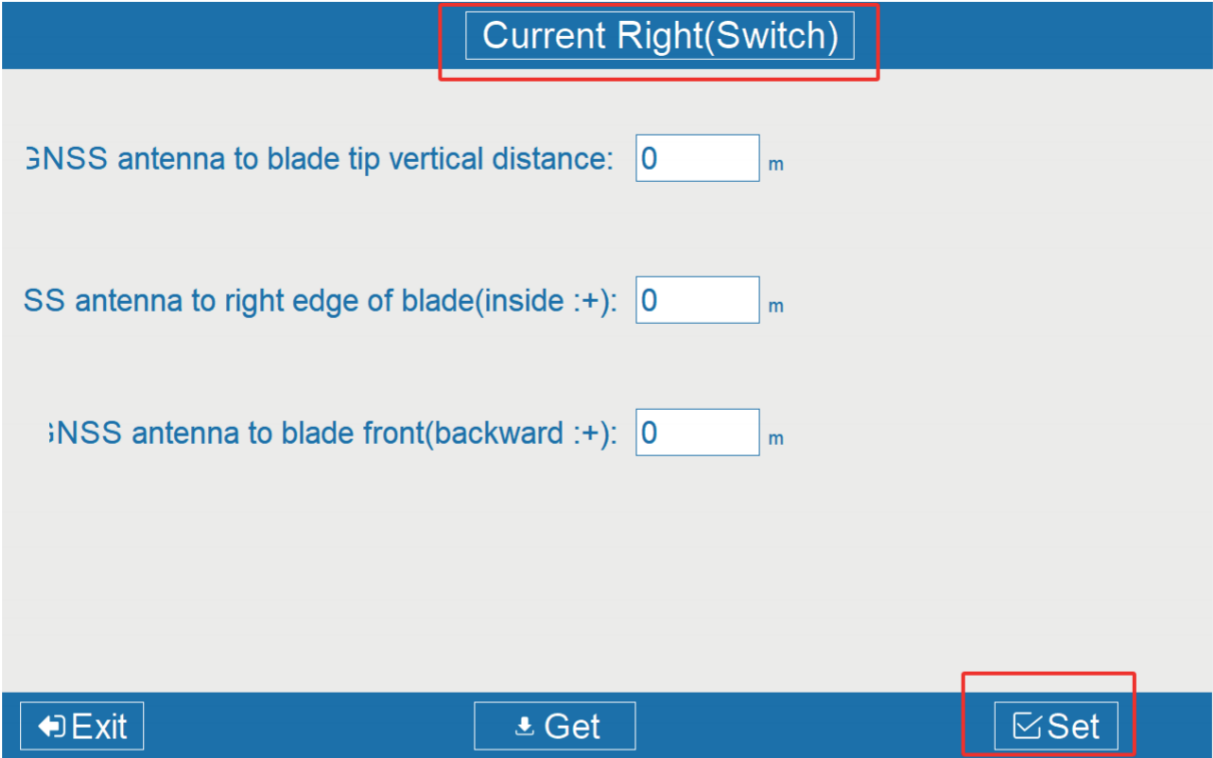


Figure 15 Click “Switch” and Set the Right Blade Parameters

3.4 RTK Status and Blade Coordinates

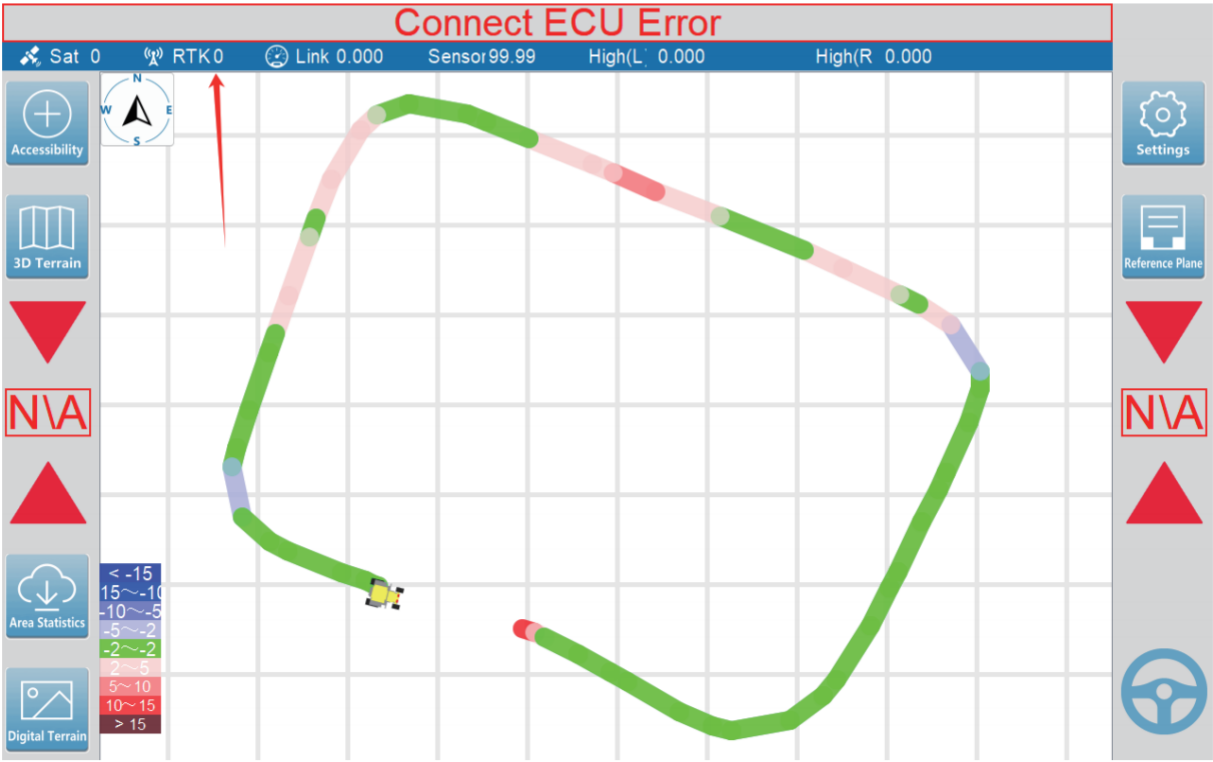


Figure 16: RTK Fixed Solution (Number = 4)

3. Basic Settings

Click Setting - System Tools - GNSS

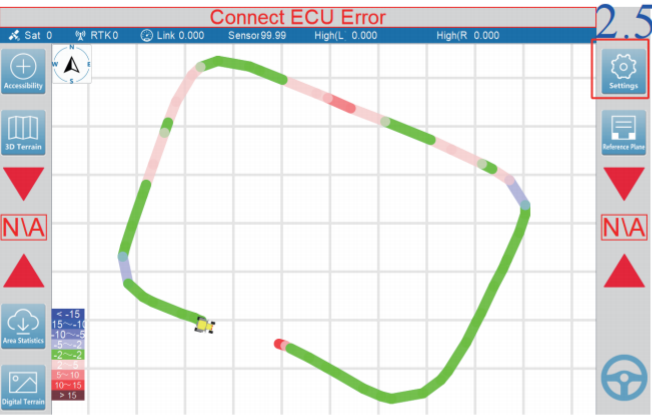


Figure 17 Settings

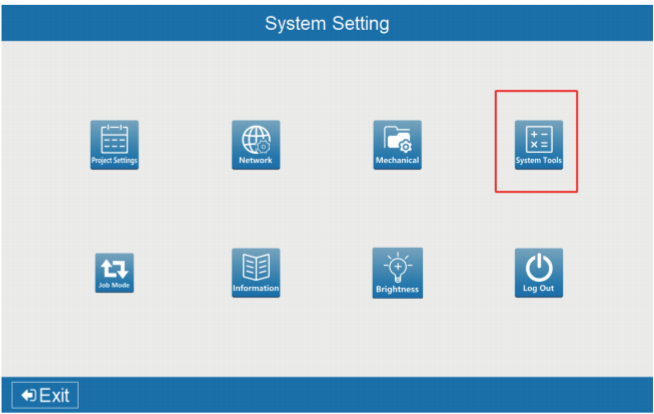


Figure 18 System Tools

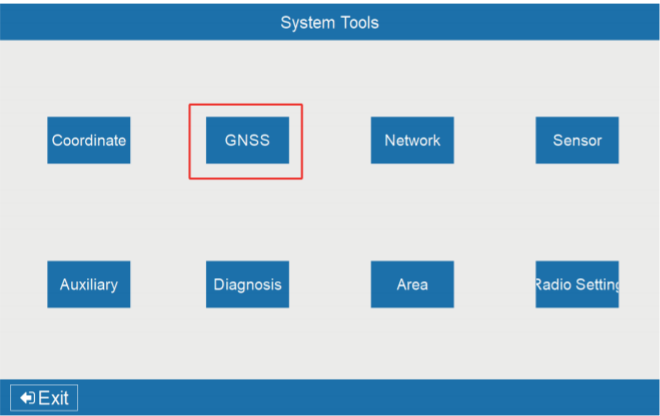


Figure 19 GNSS

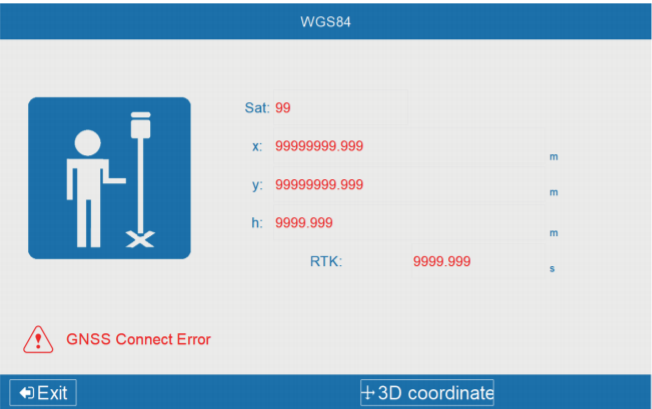


Figure 20 3D Coordinate

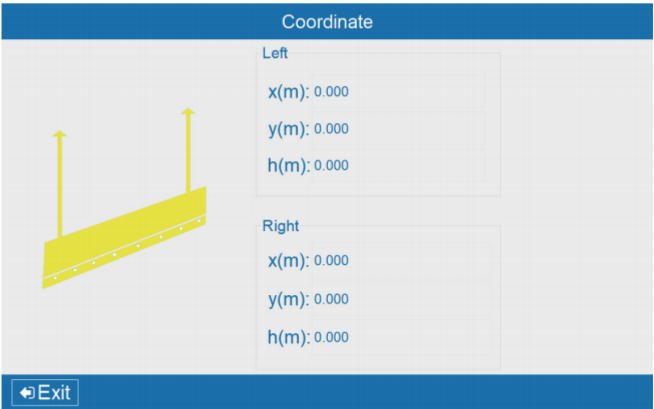


Figure 21 3D Coordinate

3. Basic Settings

3.5 Three modes: Plane/Slope/Design Mode

Click Project Settings

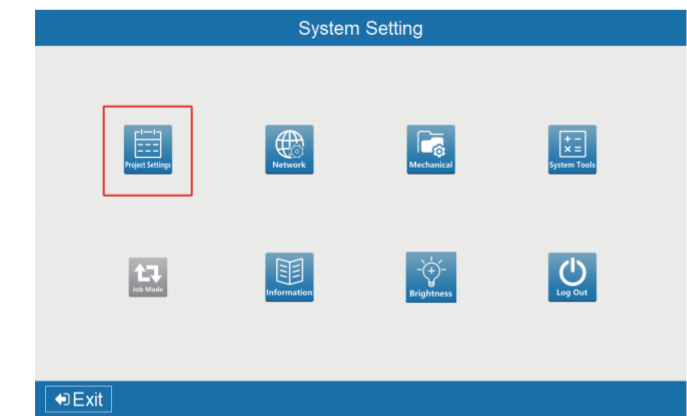


Figure 22 Project Settings

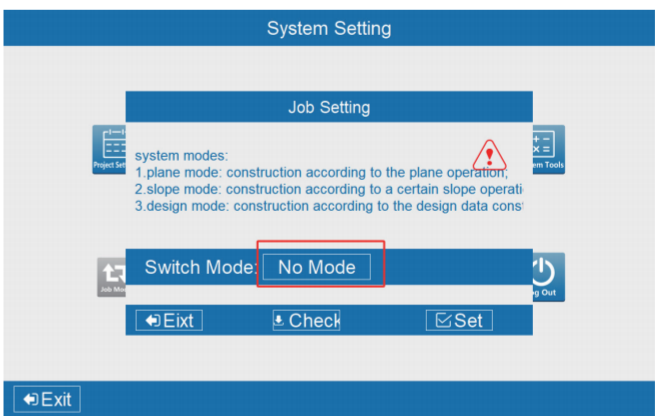


Figure 23 Click the Icon to Switch the Mode

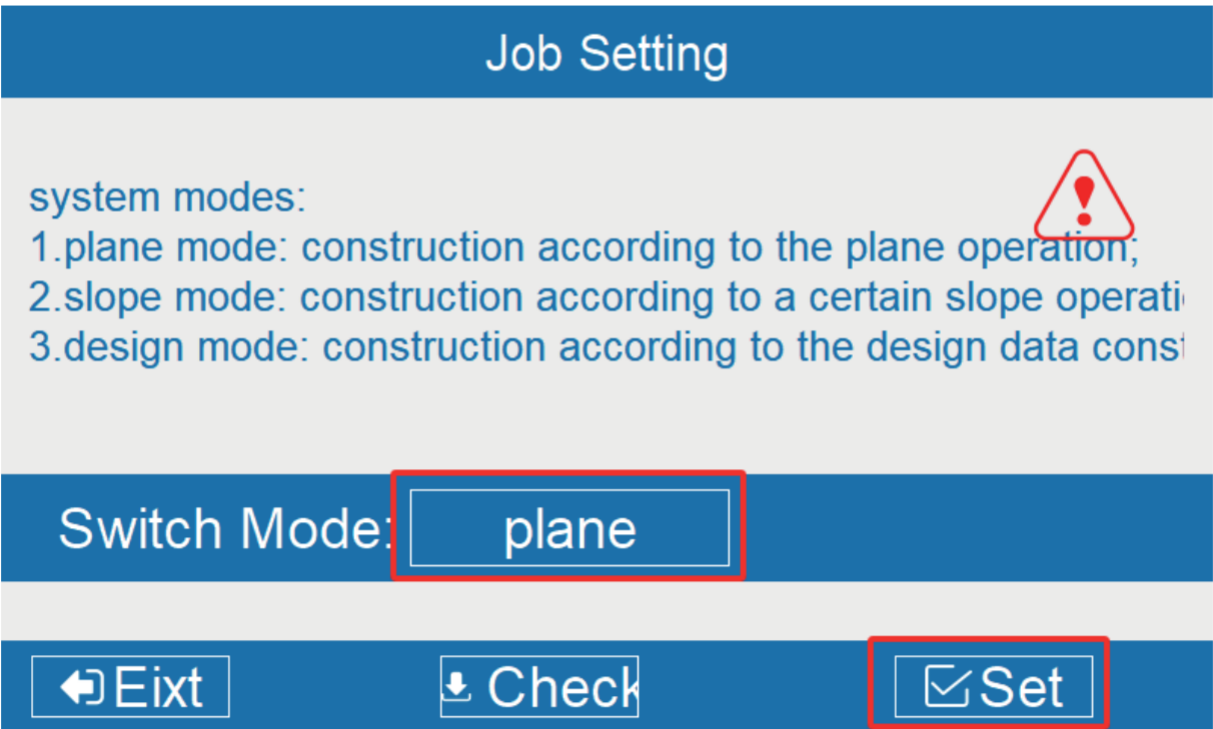


Figure 24 Plane Mode

3. Basic Settings

Plane Setting

Set Offset

Left: 0 m

Right: 0 m

Set Left

Set Right

Base Setting

Left m 0.000

Right m 0.000

Set Base

Adjust Base

GNSS

WGS84

Sat: 99

x: 99999999.999 m

y: 99999999.999 m

h: 9999.999 m

GNSS Connect Error

Exit

Figure 25 Plane Setting

Set Base: Reference plane: Current Height
Adjust Base: Manually Enter the Parameters.

Job Setting

system modes:

1.plane mode: construction according to the plane operation;

2.slope mode: construction according to a certain slope operation;

3.design mode: construction according to the design data construction;

Switch Mode

slope

Exit

Check

Set

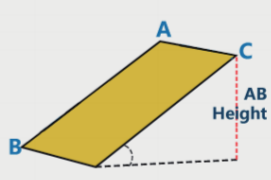
Figure 26 Slope Mode

3. Basic Settings

Slope Setting

点	x	y	h
A	0	0	0
B	0	0	0
C	0	0	0

one slope



Note: After setting point A, you need to reset point B, point and set the height difference

GNSS Connect Error

Notice: Set One Or Two Slope Switch - one slope

Slope High

AB high: 0 m

☒ Set A

☒ Set B

☒ Set C

☒ Set High

Figure 27 Slope Setting

Job Setting

system modes:

1. plane mode: construction according to the plane operation;

2. slope mode: construction according to a certain slope operation;

3. design mode: construction according to the design data construction;

Switch Mode:

design

☒ Set

Figure 28 Design Mode

3. Basic Settings

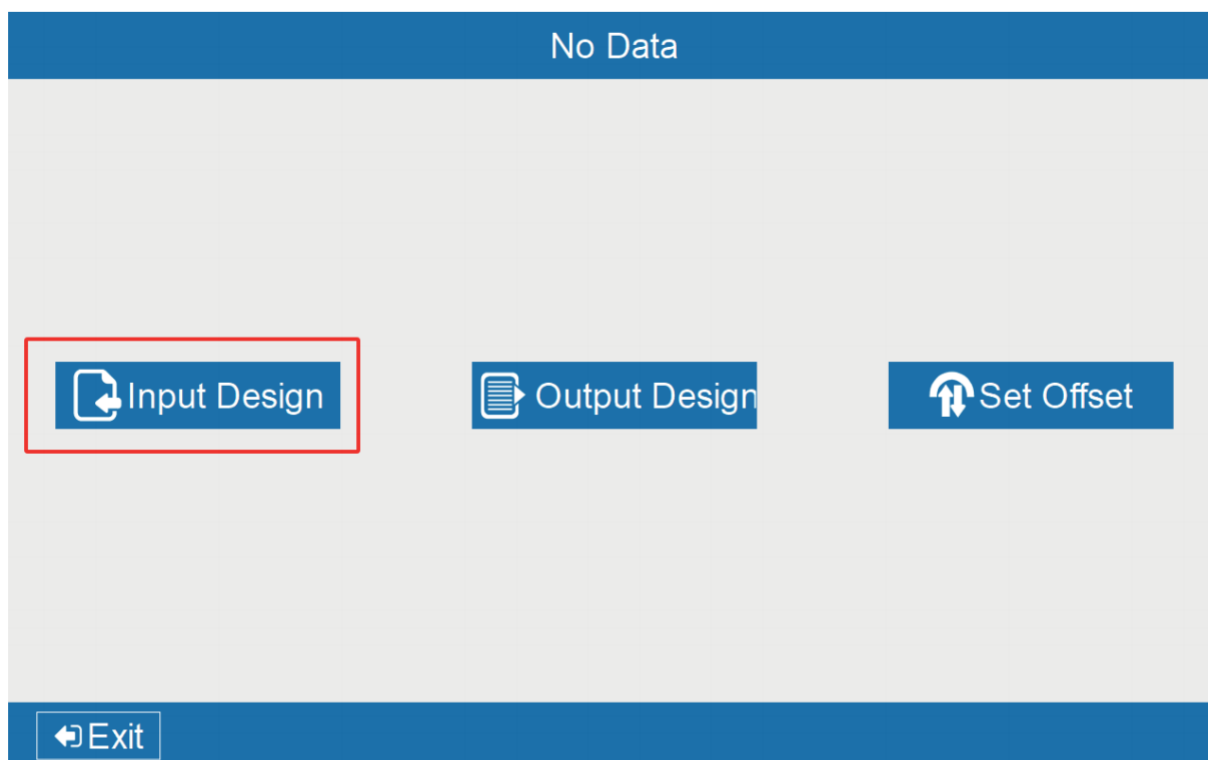


Figure 29
Input Design (Import USB data to tablet.
Supported formats: .tdt; .tdr; .tdp; .tds; .dxf.)